
Impact of Turbulence on Unmanned Aerial Vehicles

Larry B. Cornman

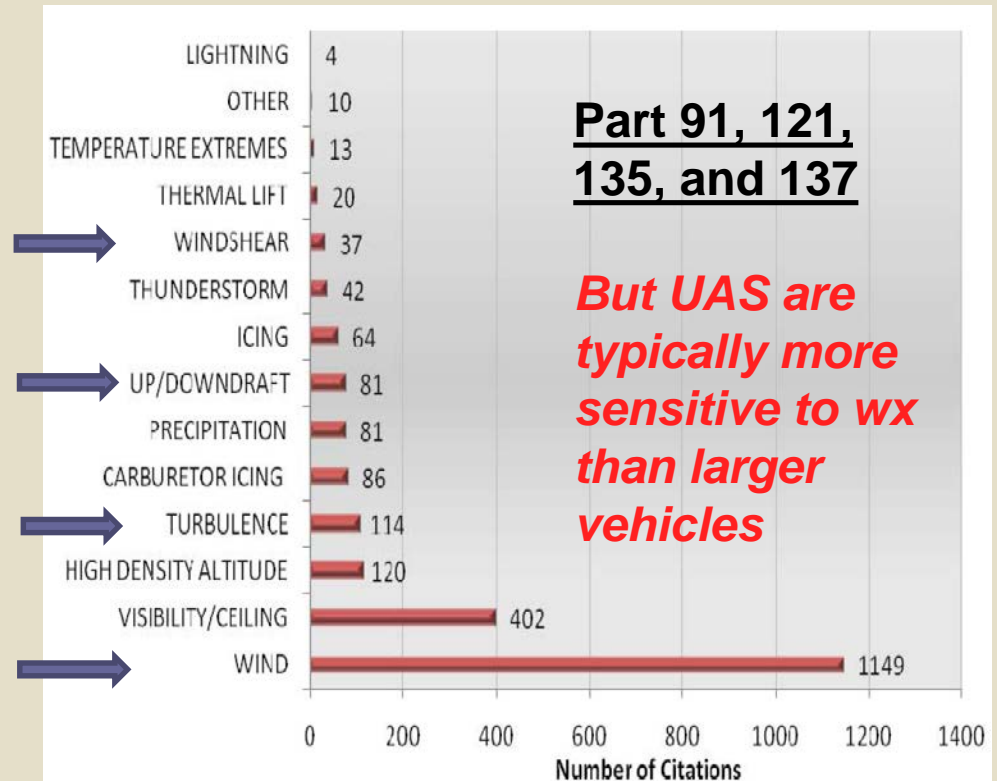
National Center for Atmospheric Research

Weather impacts on UAS operations

■ Key Wx factors:

- Steady wind: headwind, tailwind, crosswind
- Wind shear
- Turbulence and discrete gusts
- C&V
- Heavy precip.
- Icing
- Air density
- Temperature

FAA Weather Related Aviation Accident Study
2003-2007



**Part 91, 121,
135, and 137**

But UAS are typically more sensitive to wx than larger vehicles

➡ = Wind-Related

Source:
NTSB Aviation Accident
and Incident Database

Most UAS are small, rigid, light, and slow moving => high sensitivity to wind gusts

- Quadcopter in gusty conditions

source: <https://youtu.be/h-s9RbKNUyE>



- Fixed wing UAS: w/ and w/o autopilot

courtesy, RMIT UAS Research Team (RUASRT), RMIT©



Fixed-wing vs. multirotor UAS

- Many fixed-wing UASs can be considered as “scaled-down” conventional aircraft.
- Most multirotor UAS are very different from conventional helicopters.

There is a large established literature regarding the effect of winds/turbulence on fixed-wing aircraft and conventional helicopters – but very little relative to multirotors & unconventional fixed-wing UAS.



Wind and turbulence impacts on airborne vehicles

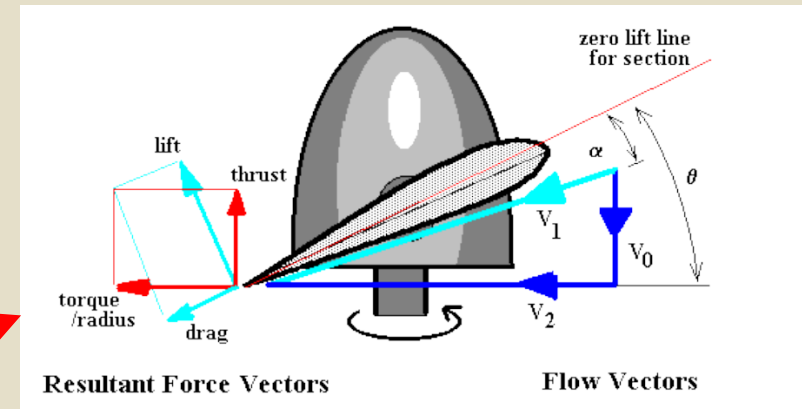
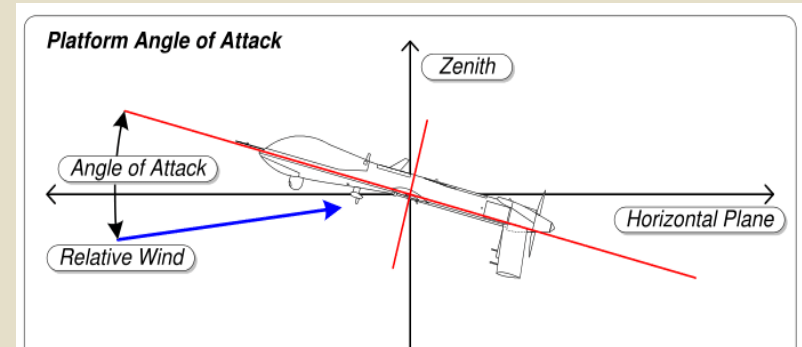
- Three classes of forces:
 - Aerodynamic
 - Propulsive
 - Gravitational

The effect of wind and turbulence are mainly manifest through aerodynamic forces

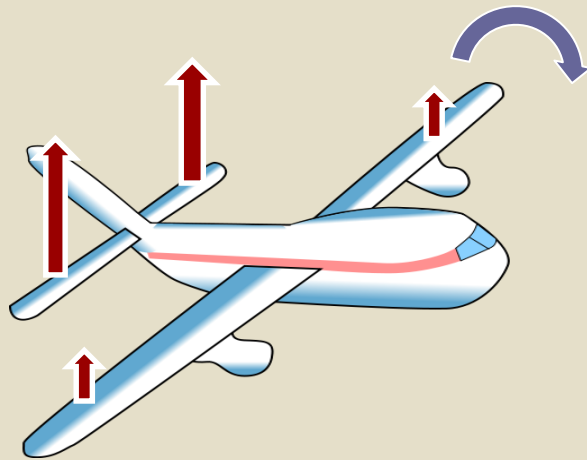
- *We consider control forces (e.g., elevator, ailerons, rudder) as aerodynamic in nature.*
- *Propulsive forces due to propellers (thrust) can also be considered aerodynamic.*

Aerodynamic forces: Lift

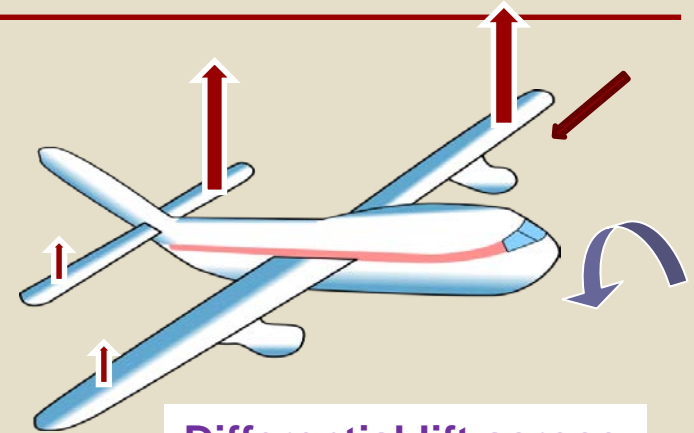
- Since an airborne vehicle must counteract gravity to stay aloft, it is the vertical component of the lift force that is key.
- The relative motion of the lifting surface through the air produces the lift
 - For *fixed-wing* vehicles, it's the forward motion of the wing and tail.
 - For *multirotors* it's the rotary motion of the propeller.



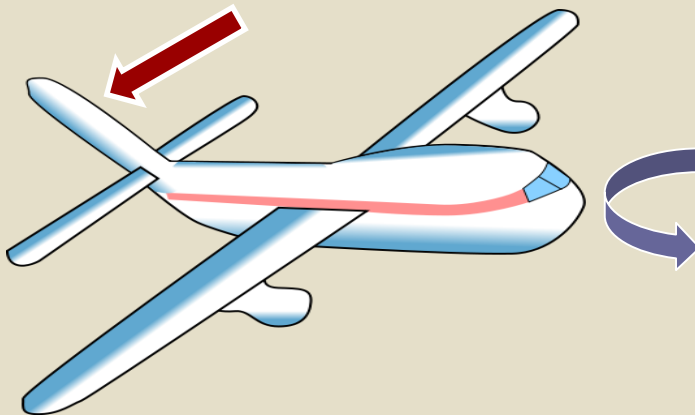
Fixed-wing vehicle: Lift forces produce translational (mainly vertical) and rotational motions



Differential lift on wing and tail produces pitching moment

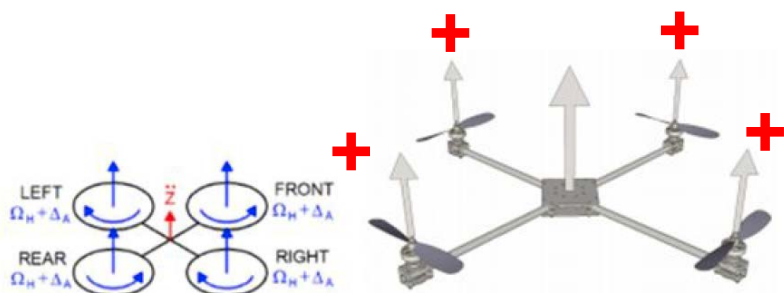


Differential lift across wing (or tail) or side wind (dihedral effect) produces rolling moment

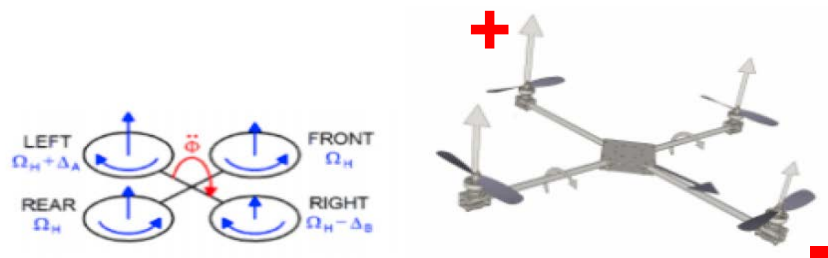


Side wind on vertical tail surface produces yawing moment

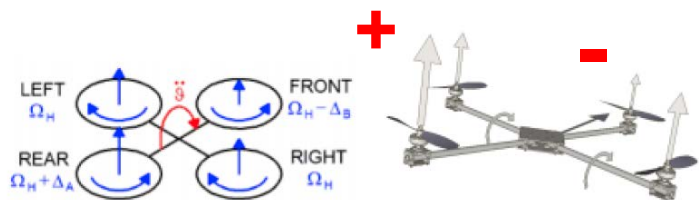
Quadrotor motion and orientation changes via differential thrust and torque



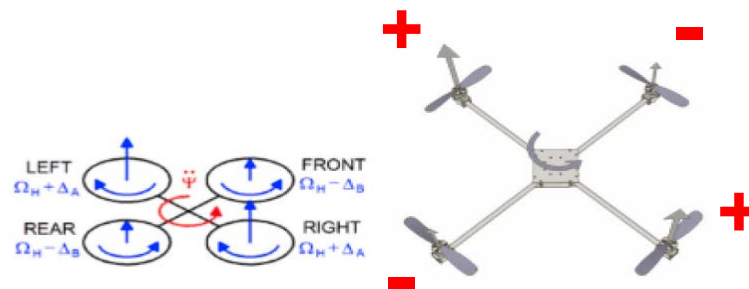
Vertical motion via uniform thrust



Rolling motion and translation via differential “left-right” thrust



Pitching motion and translation via differential “front-rear” thrust

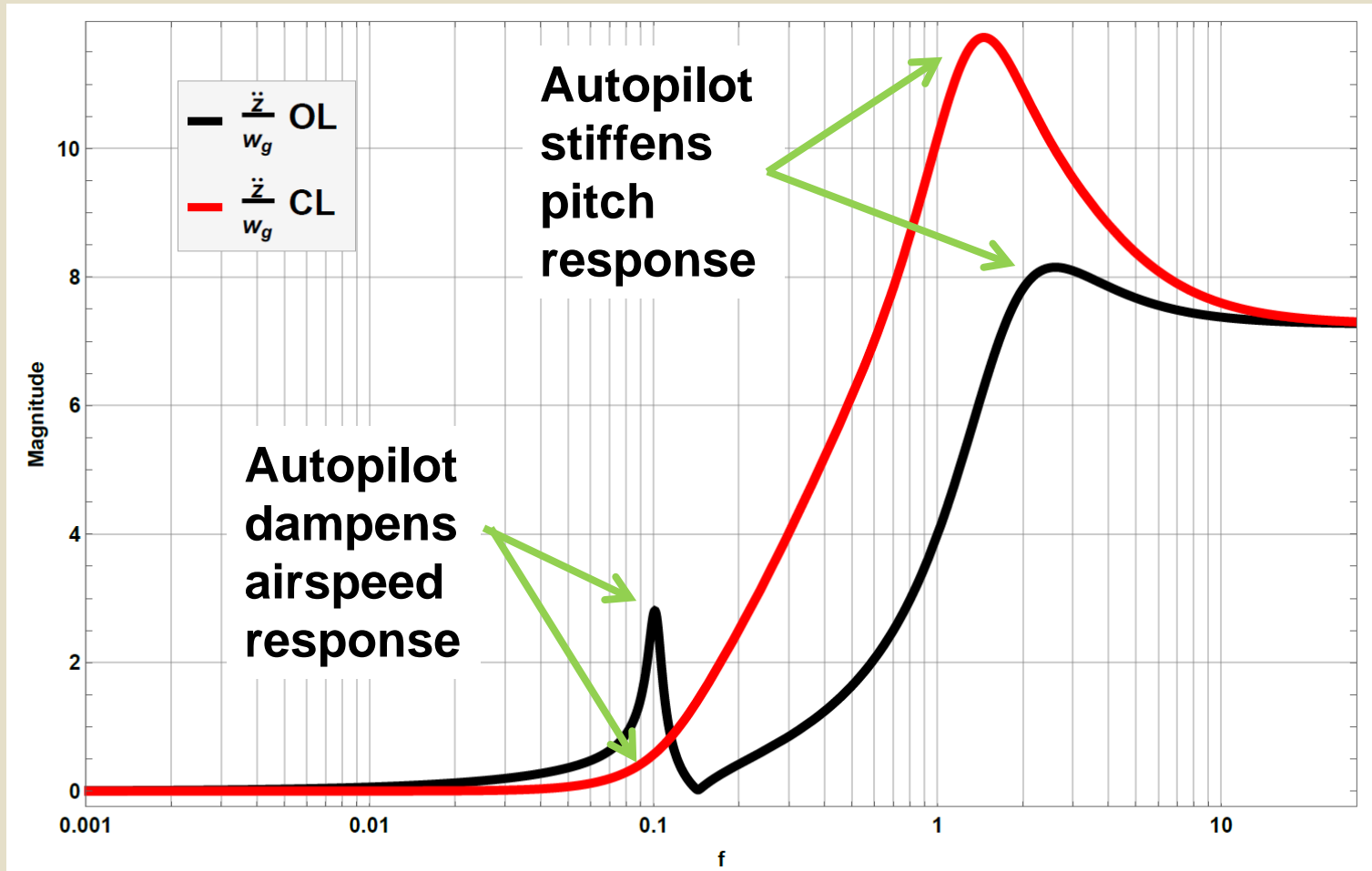


Yawing motion via adjacent-paired differential reactive torque

Modeling impact on UAS due to winds & turbulence

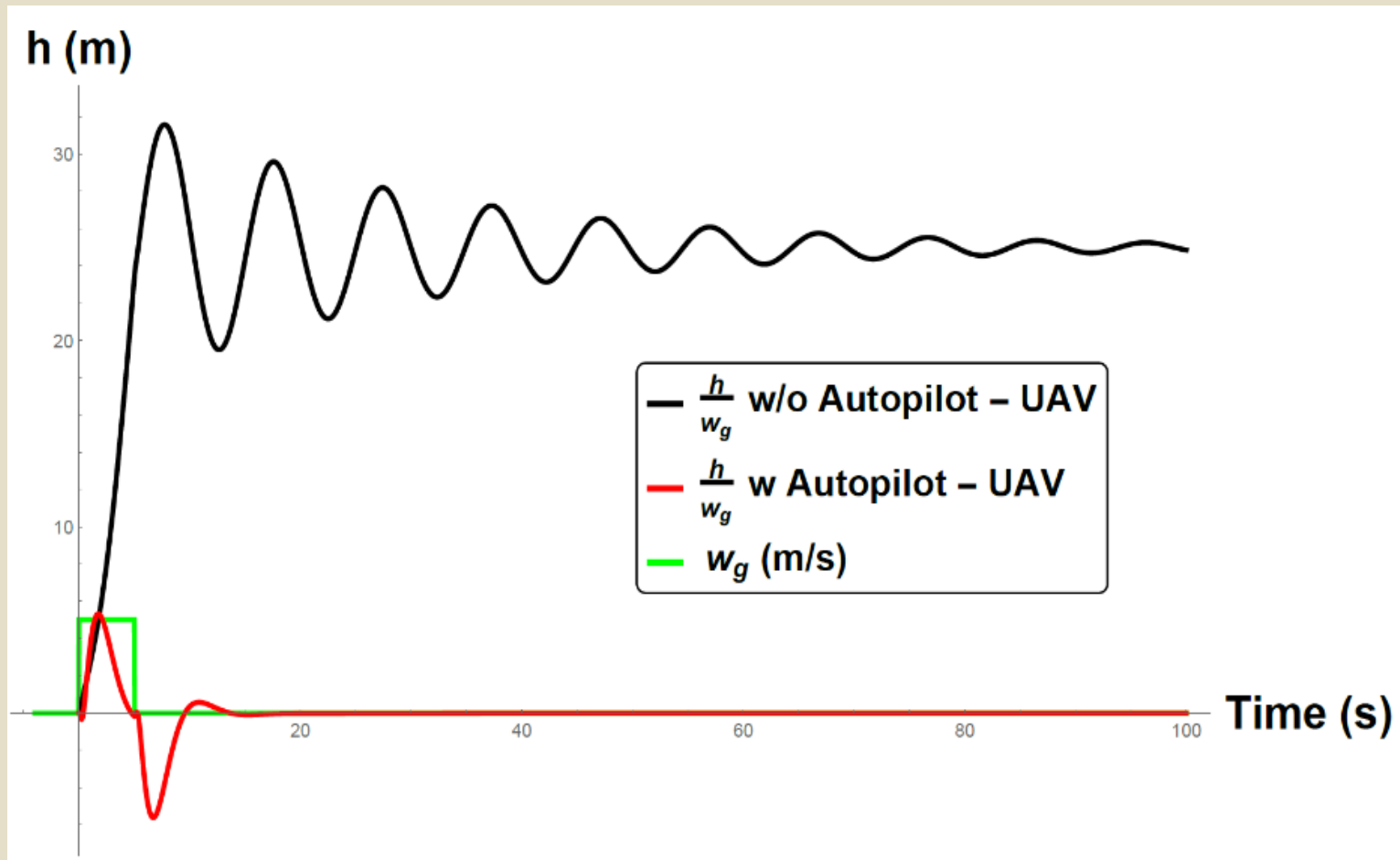
- Clearly, loss of lift resulting in large vehicle translations (e.g., hitting the ground) is important.
- For manned vehicles, another important metric is large vertical accelerations (e.g., impact on occupants, stress on vehicle).
- Not yet clear what other metrics might be relevant to UAS (e.g., large attitude changes that result in stability & control problems).

Autopilot has a significant effect on vertical acceleration response to vertical gust



Small UAV

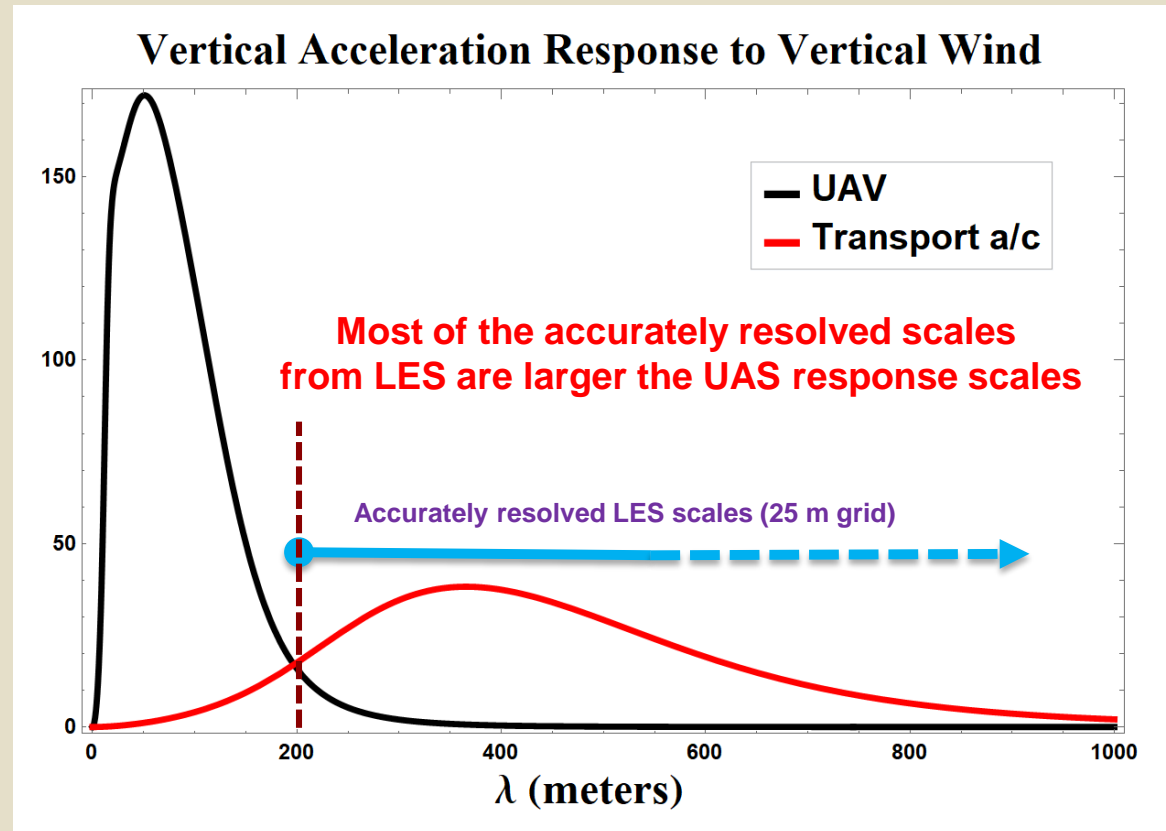
Autopilot has a dramatic effect on UAS height response to vertical gust



Vertical Displacement Response to Updraft

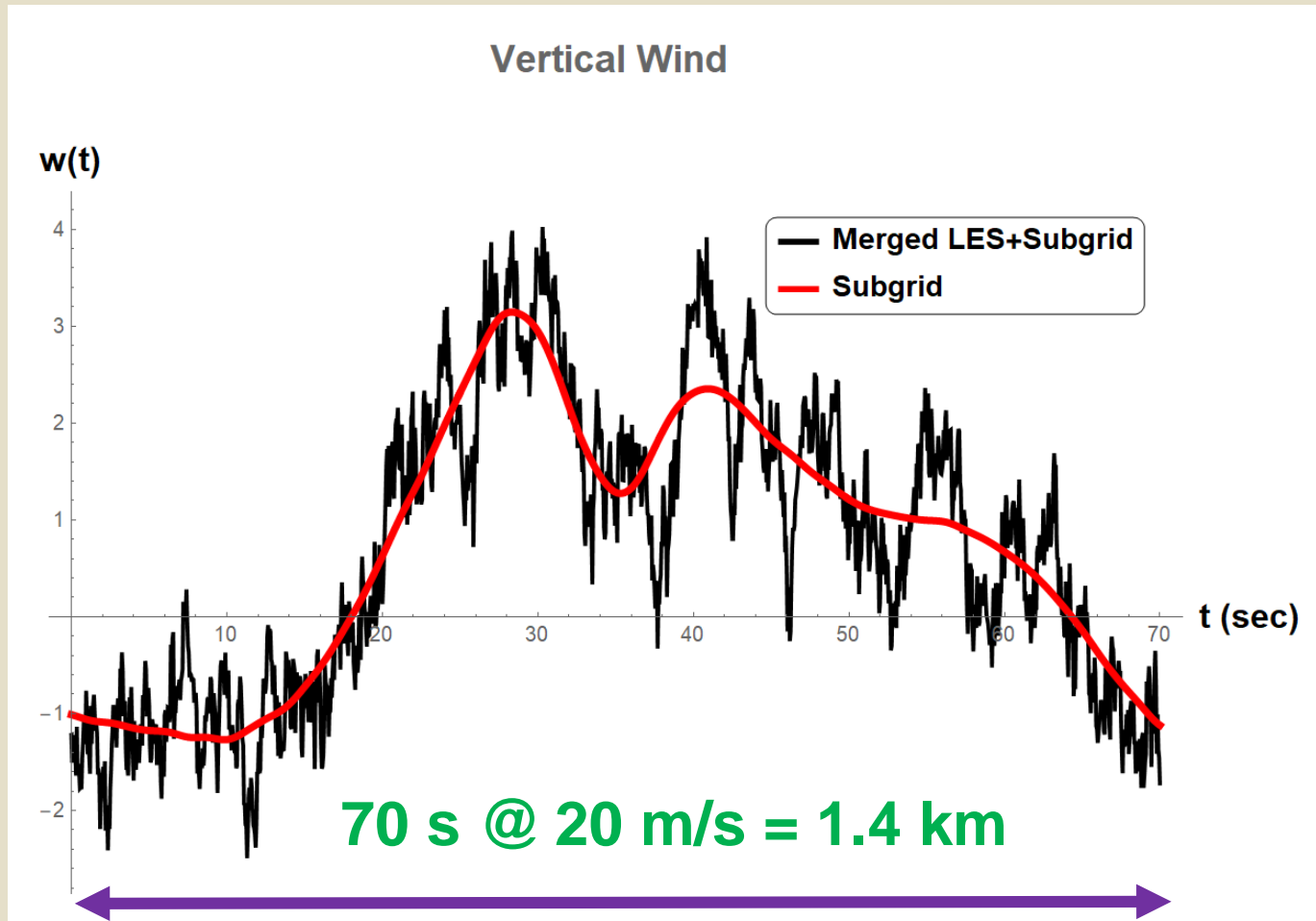
The importance of including realistic winds in UAS flight modeling and simulation

- Accurate UAS flight simulation requires accurate winds at UAS scales (m-10's m).
- LES model output is inherently filtered; e.g., 25 m spatial resolution results in accurate winds at ~200 m.



Solution: merge LES wind with subgrid turbulence

LES + subgrid merging example

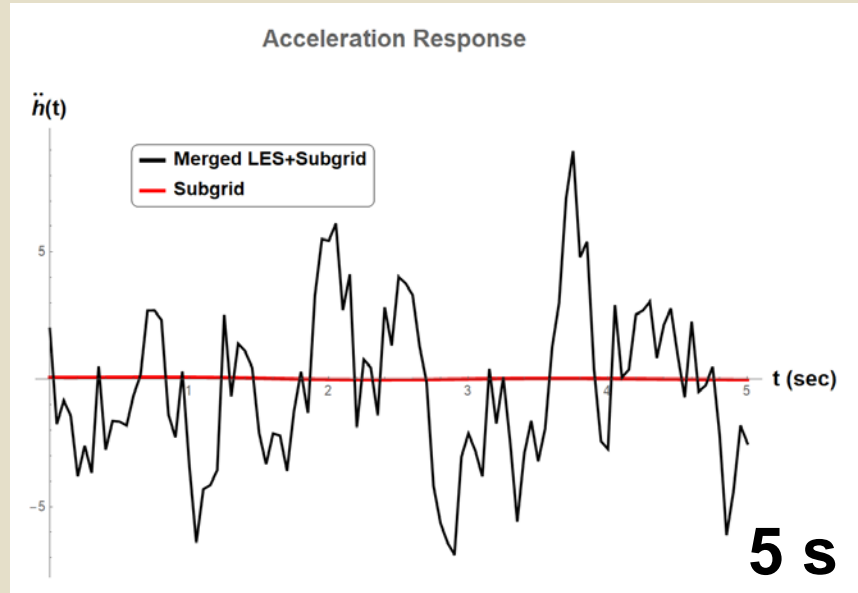
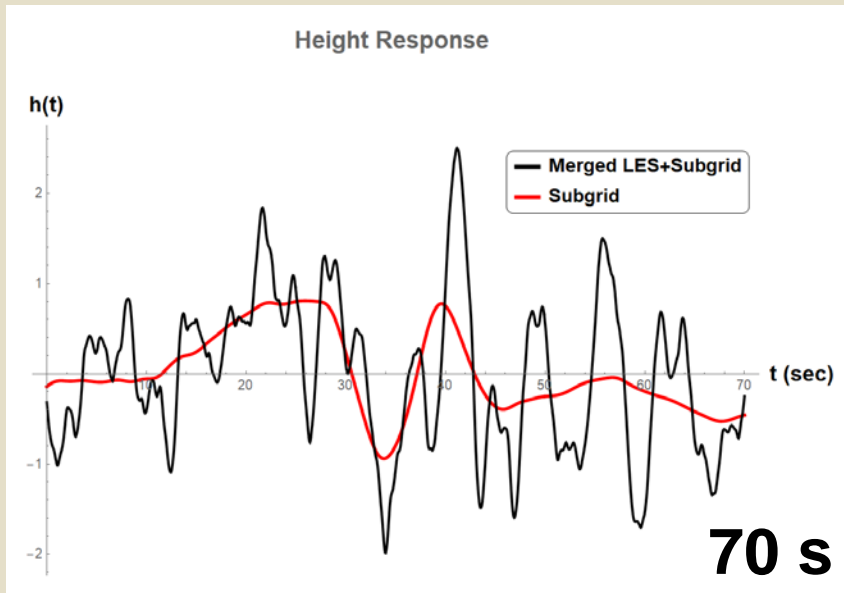


Result: realistic large and small scale wind

UAS simulation through LES and LES+subgrid wind fields

Height Response

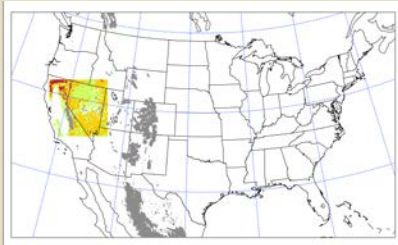
Acceleration Response



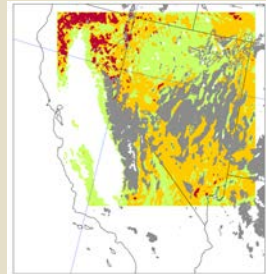
Using LES-only gives ballpark results for height, but is inadequate for acceleration simulation

Application of research to operations

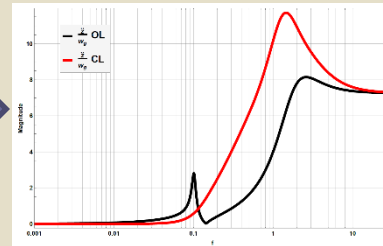
HRRR 3km
data cutout



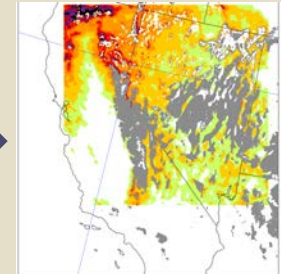
GTG Turbulence
Product



UAS turbulence
response



UAS impact
values



**Goal: End-to-End Turbulence
Forecasting/Nowcasting System
for UAS Operations**

Where do we go from here?

■ User needs assessment:

- What are the wind/turbulence impact variables of importance (performance and/or stability & control metrics)?
- What are the required temporal/spatial scales?
- What are the accuracy requirements?
- How is the information provided to users (decision support systems)?

■ Research activities:

- Vehicle modeling/simulation (fixed-wing and multirotor).
- Translation algorithms (model output -> vehicle impact).
- Flight test/demos.