# Improvement of Forest Canopy Characterization Based on NoahMP and Its Impact on Land Air Exchange Processes

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# Key processes: land-air exchange



# Key interface: canopy



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## **Vegetation morphology in different models**

**Hourly Models** 



Hanson et al, 2004; D. Baldocchi., 2016



# **Parameters of Canopy in Noah-MP**



### The canopy structure is represented by a simple geometric shape

#### MPTABLE.TBL

Used/Defined in Subroutine	Short description [units]			
CANWATER	Maximum water intercepted by canopy [mm]			
RAGRB	Leaf dimension [m]			
ENERGY	Momentum roughness length [m]			
PHENOLOGY / TWOSTREAM	Canopy top [m]			
PHENOLOGY / TWOSTREAM	Canopy bottom [m]			
TWOSTREAM	Tree density [number/m <sup>2</sup> ]			
TWOSTREAM	Crown radius [m]			
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CO2FLUX / STOMATA	Maximum foliage nitrogen factor (see FOLN setting in code) [unitless]			
CO2FLUX	Wood pool factor used to determine relative wood presence [unitless]			
CO2FLUX	Wood to non-wood ratio [kg/kg]			
CO2FLUX	Microbial respiration in fast soil carbon pool at 10°C [umol/m <sup>2</sup> /s]			
PHENOLOGY	Monthly stem area index when prescribed [m <sup>2</sup> /m <sup>2</sup> ]			
PHENOLOGY	Monthly leaf area index when prescribed [m <sup>2</sup> /m <sup>2</sup> ]			
BVOCFLUX	Stem-to-leaf area density [unitless]			
BVOCFLUX	Emission capacity for up to 5 different BVOC fluxes at 30°C [ug C/g foliar mass/hour]			
	Used/Defined in Subroutine CANWATER RAGRB ENERGY PHENOLOGY / TWOSTREAM PHENOLOGY / TWOSTREAM TWOSTREAM CO2FLUX / STOMATA CO2FLUX CO2FLUX CO2FLUX PHENOLOGY PHENOLOGY BVOCFLUX BVOCFLUX			



# The canopy data by earth observation



费心

## How to get canopy parameters in our study forest?

#### Sample site, Subtropical forests in Guangdong, China



### FluxTower



# **Using UAV-based Photogrammetry**



## **Correction of canopy parameters and its effects**



M Chang, et al. Remote Sensing. 2020

# How to get more accuracy canopy parameters?

### Light Detection and Ranging (LiDAR)



- WAXiand Aisborned DARifferent
- altigedae der aegopy.
- Less affected by occlusions and
  High flexibility
- Figh flexibility shadows, can penetrate the canopy
- Large range of acquired data information.



Guo et al., 2021<sub>11</sub>

# **UAVs and LiDAR setup**



- Active remote sensing: unmanned airborne lidar
- Passive optical remote sensing: visible light drones



- Flight altitude: 100 metres from the landing site
- Flight speed: 4.3 m/s
- Average sampling distance: 7.24 cm

- Heading overlap: 80.0%
- Scanning angle: 37° and 70°

(b)	Initial image positions <ul> <li>Computed image positions</li> <li>(i) <ul> <li>(i)</li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul></li></ul>	C	
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Relative geographic accuracy
 X: 95.0% Y: 100.0% Z: 100.0%

## Single Tree Segmentation of Point Cloud in Sample Land Surveying





## **Characteristics of field canopy structure**



Average values of the canopy structure

	LPR	VPR	Observed (Reference)
Average tree height ( <mark>HVT</mark> , m)	$16.35 \pm 2.19$	16.02 ± 7.07	7.0~16.7
The diameter at breast height ( <mark>DBH</mark> , cm)	2.22 ± 1.92	1.48 ± 1.60	5.1~21.9
Canopy radius ( <mark>RC</mark> , m)	3.92 ± 1.78	4.80 ± 2.35	3.0~16.0
Leaf area index (LAI)	$4.28\pm2.38$	0.48 ± 0.43	$6.5\pm0.7$
Canopy cover	0.81 ± 0.18	0.48 ± 0.32	>0.8
Gap fraction	0.19 ± 0.18	$052\pm0.42$	0.1~0.2

### LPR: LiDAR Photogrammetry Results VPR: Visible-light Photogrammetry Results

• Passive optical remote sensing has major limitations in establishing a link with vegetation.

# Correction of canopy parameters by using fitting function



- Relationship between average tree height (HVT) and Canopy radius (RC) driven by (a) LPR and (b) VPR.
- Red lines indicate linear fits.

#### HVT and RC functions for Noah-MP inputs

Variables	Default	LPR	VPR
HVT	16.0	HVT from LPR	HVT from VPR
RC	1.4	$-0.09 \times HVT + 0.01 \times HVT^{2} + 3.21$	-11.82 × 0.92 <sup>HVT</sup> + 12.29

# **Results of the simulated canopy temperature and humidity profiles**



GT Wu et al. Remote Sensing. 2022

## **Diagnosis of the radiation and heat fluxes**



GT Wu et al. Remote Sensing. 2022

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## **Parameters vs OPT\_RAD option choice**

Experimental name	Vegetation canopy parameters	Vegetation canopy structure programme options
D_1		Three-dimensional (3D) canopy morphology
D_2	Default	Non-vegetated gap
D_3		Coverage-based
LPR_1	LPR	Three-dimensional (3D) canopy morphology
LPR_2		Non-vegetated gap
LPR_3		Coverage-based
VPR_1	VPR	Three-dimensional (3D) canopy morphology
VPR_2		Non-vegetated gap
VPR_3		Coverage-based

### Canopy 3D Morphology with LiDAR Photogrammetry Parameter inputs have Lower RMSE for radiation



• The upward shortwave radiation and upward longwave radiation RMSEs simulated by the LPR are reduced by 9.5% and 3.6% compared to the VPR.

### Canopy 3D Morphology with LiDAR Photogrammetry Parameter inputs have Lower RMSE for latent heat flux



• The upward shortwave radiation and upward longwave radiation RMSEs simulated by the LPR are reduced by 9.5% and 3.6% compared to the VPR.

## **Current Mechanism**

#### **Considering canopy gaps** $P_{\rm bc} = e^{\frac{-\rho_{\rm t} \times \pi \times r^2}{\cos(\theta')^2}}$ $P_c$ : total canopy gap probability $P_{c} = min \begin{cases} 1 - F_{veg} \\ P_{bc} + P_{wc} \end{cases}$ between-crown gap probability $K_{open} = 0.05$ $\rho_t = -\frac{\log(\max(1.0 - F_{veg}, 0.01))}{\pi \times u^2}$ K<sub>open</sub>: gap fraction $\theta' = \tan^{-1}\left[\frac{H_{top} - H_{bot}}{2\pi} \times \tan\theta\right]$ $F_{veg}$ : veg fraction within-Crown Gap r: tree crown radius **Probability** *H<sub>top</sub>*: height to canopy top No canopy gaps H<sub>bot</sub>: height to canopy bottom $P_{c} = 0$ $-0.5 \times F_a \times (H_{top} - H_{bot})$ $K_{open} = 0$ $\cos\theta$ $\cdots P_{wc} = (1 - P_{hc}) \times e$



# Further work 1: Expressing more refined canopy structure and processes in the model

Extractable from UAV-based photogrammetry: Height, Length, Volume, Coverage Canopy closure, Leaf area index, Gap rate, Biomass…



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# Further work 2: expressing and comparing from other scales



# **Related Papers**

- M Chang, JC Cao, Qi Zhang, WH Chen, GT Wu, LP Wu, WW WANG, XM Wang\*, Improvement of stomatal resistance and photosynthesis mechanism of Noah-MP-WDDM (v1.42) in the simulation of NO<sub>2</sub> dry deposition velocity in forests, Geoscientific Model Development, 2022. 15(2):787-801.
- GT W, YC Y, YB Y, JC Cao, YJ Bai, SJ Zhu, LP Wu, WW Wang, M Chang\* and XM Wang, UAV-LiDAR Measurement of Vegetation Canopy Structure Parameters and Their Impact on Land-Air Exchange Simulation Based on Noah-MP Model, Remote Sensing, 2022. 14(13):2998.
- M Chang, SJ Zhu, JC Cao, BY Chen, Qi Zhang, WH Chen, SG Jia, Krishnan Padmaja, XM Wang\*. Improvement and Impacts of Forest Canopy Parameters on Noah-MP Land Surface Model from UAV-Based Photogrammetry. Remote Sensing. 2020, 12, 4120.
- M Chang, WH Liao, XM Wang\*, Q Zhang, WH Chen, ZY Wu. An optimal ensemble of the Noah-MP land surface model for simulating surface heat fluxes over a typical subtropical forest in South China. Agricultural and Forest Meteorology. 2019, 281: 107815.



