



Demonstrating the Value of Adding Suction Losses for Channel Infiltration in WRF-Hydro Hydrological Model and Its Application in Semiarid Region

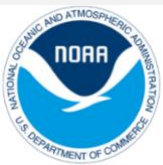


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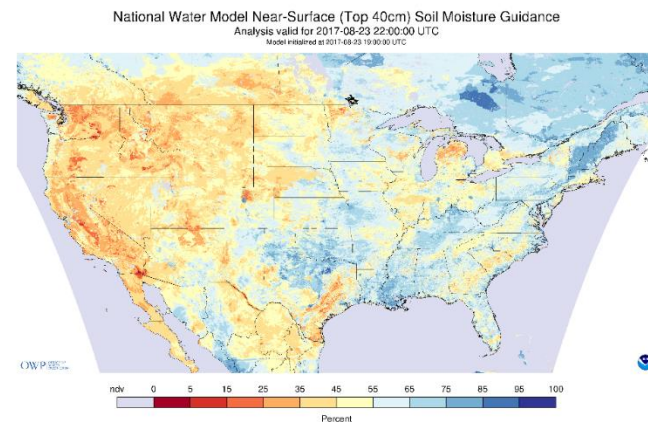
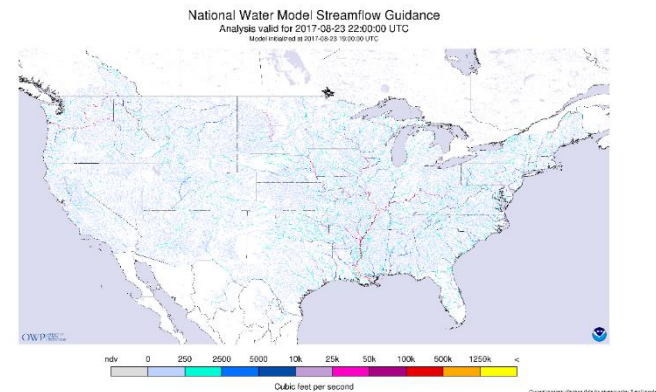
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Introduction

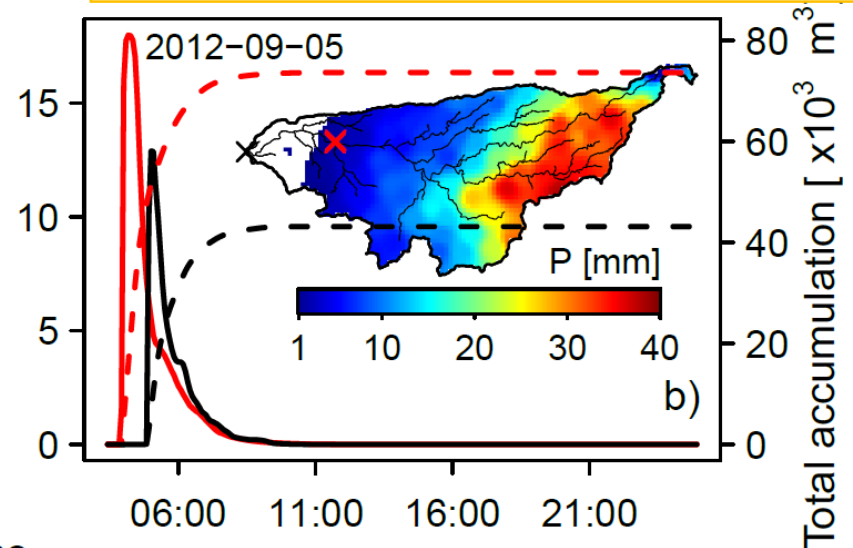
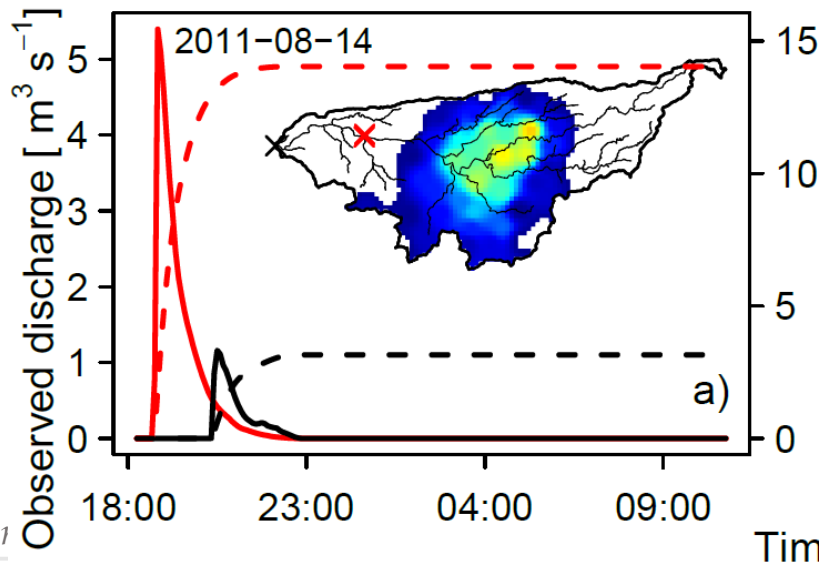
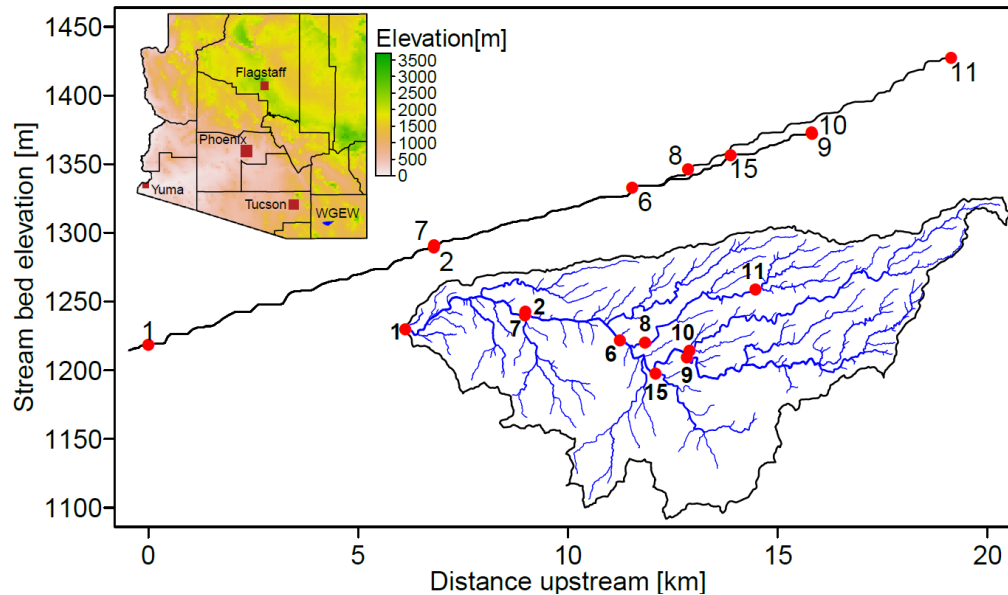
- The WRF-Hydro hydrological model (Gochis et al. 2018) configured as NOAA National Water Model (NWM) is *challenged to reproduce* hydrologic responses (infiltration losses) in southwestern CONUS.
- NWM Background
 - Need for an NWM: Human Cost of Flood Events
 - \$7.96 Billion Per Year
 - 82 Fatalities Per Year
 - Hydrologic model simulation for the entire Contiguous US
 - Analysis: Hourly streamflow based on observed precipitation
 - Forecasts: Numerical Weather Prediction models used as forcing.
- NWM Data Samples



Impact of infiltration at catchment scale

USDA-ARS Walnut Gulch Experiment Watershed

- Observational runoff data in Walnut Gulch Experimental Watershed (WGEW) shows the transmission losses in channel.
- Channel infiltration is identified to be a major physical process that controls the water balance in semiarid regions.




KINEROS2: Mathematical Formulation

KINEROS2: A KINEMATIC RUNOFF and EROSION MODEL (USDA-ARS)

Surface is assumed as ponded at initial condition ($t = 0$)

$$f_c = K_s \left[1 + \frac{\alpha}{\exp\left[\frac{I' \alpha}{\Delta \theta G}\right] - 1} \right]$$


**Gravity
Effect** **Suction
Effect**

f_c : Channel Infiltrability

K_s : Saturated Hydraulic Conductivity

G : Capillary Drive

$I'(t)$: Cumulative Infiltration Depth

θ_s : Saturated Soil Water Content

θ_i : Initial Soil Water Content

α : Soil Type Parameter (range from 0 to 1)

$$G = \frac{1}{K_s} \int_{-\infty}^0 K(\varphi) d\varphi$$

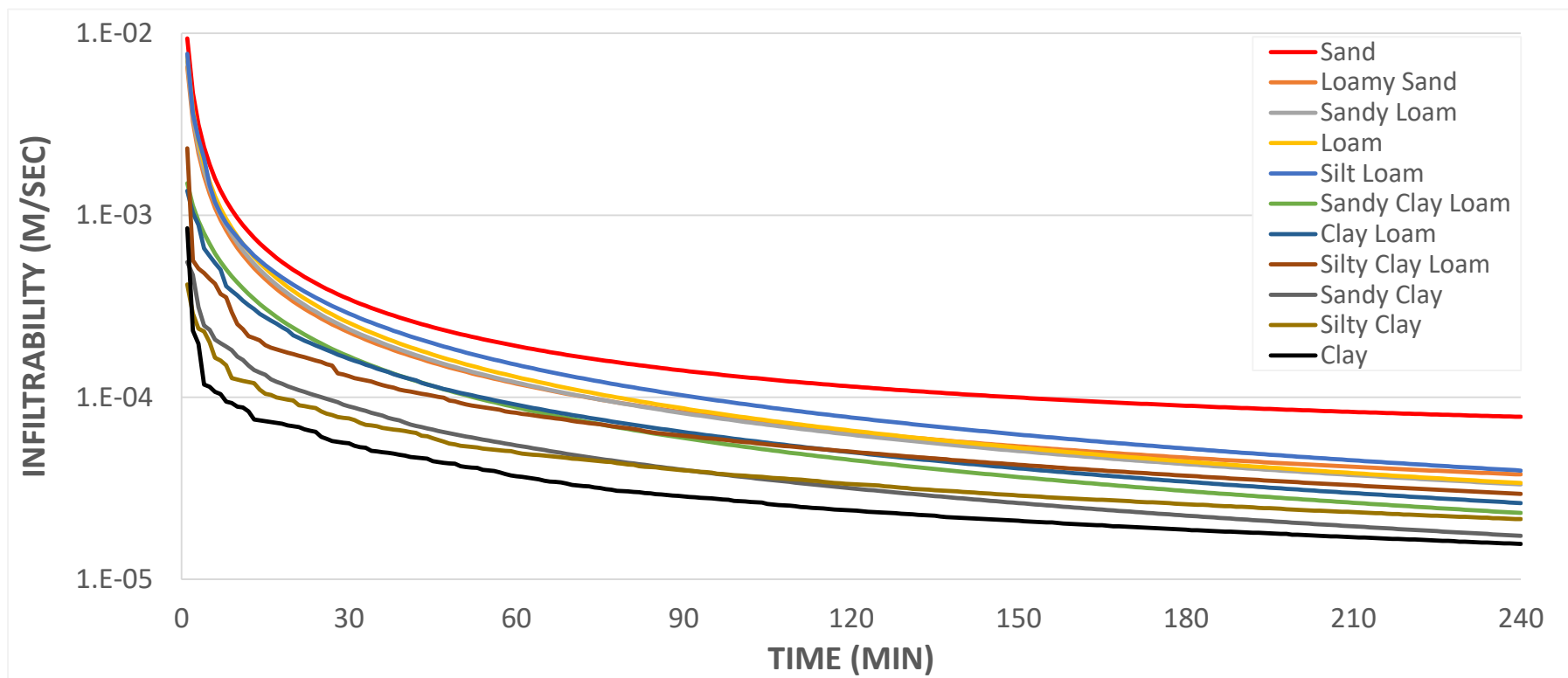
Note:

$$I = \frac{G \Delta \theta}{\alpha} \ln \left[\frac{f_c - K_s + \alpha K_s}{f_c - K_s} \right] + K_i t \rightarrow I'(t) = \frac{G \Delta \theta}{\alpha} \ln \left[\frac{f_c - K_s + \alpha K_s}{f_c - K_s} \right]$$

$\alpha = 0 \rightarrow$ Green-Ampt; $\alpha = 1 \rightarrow$ Smith-Parlange

KINEROS2 recommends $\alpha=0.80$

Time-Variant Channel Infiltrability



Time-Variant Infiltrability shows:

- ✓ The suction affects most at the *first 30 min*.
- ✓ *Overall* effect extends to around *120 min (2hr)*.
- ✓ After around 180 min (3hr), Infiltrability approaches to saturated hydraulic conductivity

Model Re-initialization

- KINEROS2 is an event oriented, physically based model, so it needs to be re-initialized.
- Three Parameter Infiltration Equation:

$$f_c = K_s \left[1 + \frac{\alpha}{\exp\left[\frac{I'\alpha}{\Delta\theta G}\right] - 1} \right] \quad I'(t) = \frac{G\Delta\theta}{\alpha} \ln \left[\frac{f_c - K_s + \alpha K_s}{f_c - K_s} \right]$$

Current Research:

- ✓ $I'(t)$ exponentially returns to “zero” within “2” days (2880 min)

$$I'(t) = ae^{b(t-t_0)}; \quad a = I_{total}; \quad b = \ln \frac{\left[\frac{I_{5min}}{I_{total}} \right]}{2880 \text{ (min)}}$$

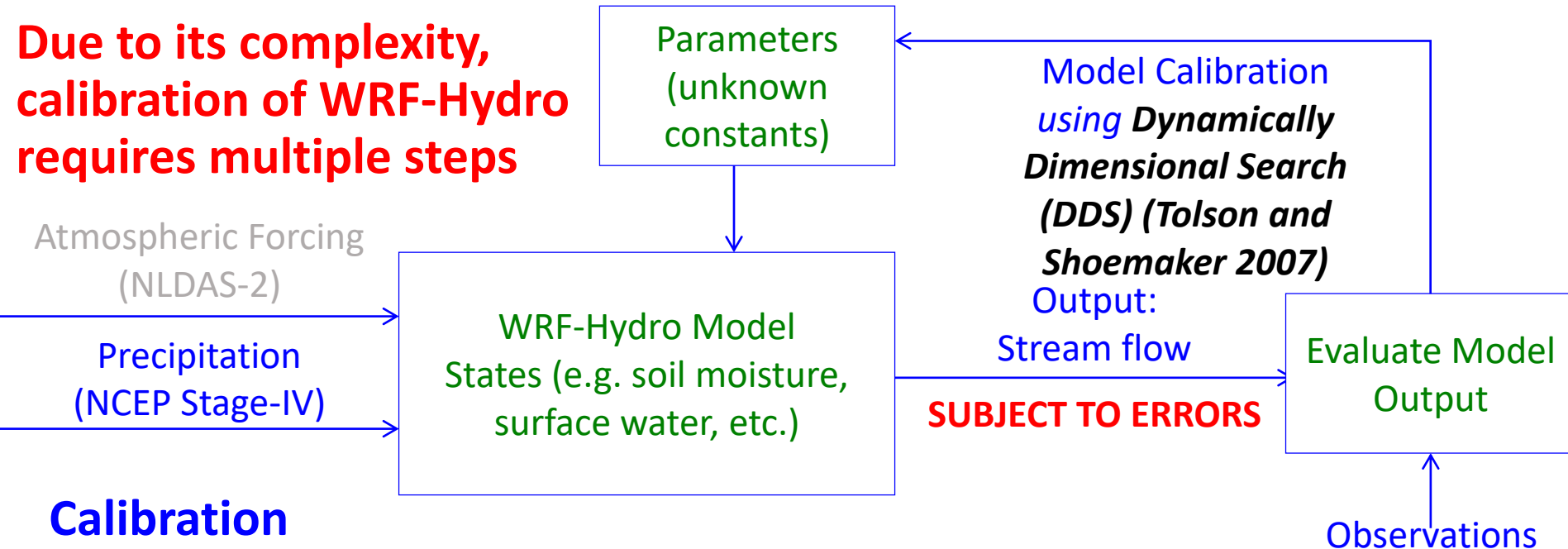
I_{total} : Total cumulative infiltration depth during one single flow event

I_{5min} : The first five minute cumulative infiltration depth

There are multiple other ways to solve this problem.

Event-Based Calibration in WGEW

Due to its complexity, calibration of WRF-Hydro requires multiple steps



Calibration

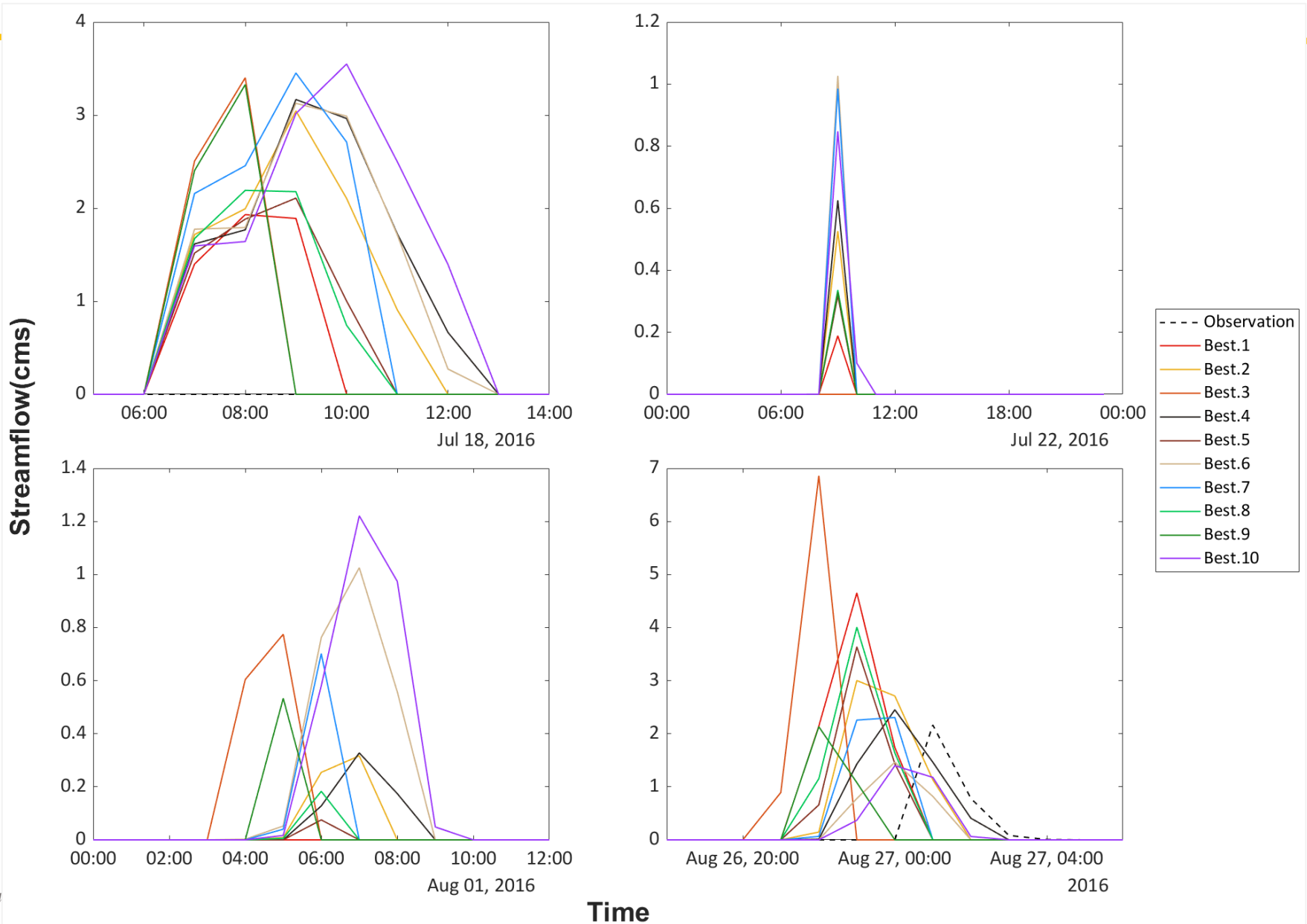
- Choose Walnut Gulch Experiment Watershed as illustrative example
- Spin up Period ranges from Jun 1st 2014 to May 31st 2016
- Calibration Period ranges from Jun 1st 2016 to Aug 31st 2016
- Calibration based on basin outlet using Kling Gupta Efficiency (KGE) objective function and total of 250 DDS steps
- Repeat the same procedure for 10 times

Name	Description	Units
Soil Parameters		
BEXP	Pore size distribution index	dimensionless
SMCMAX	Saturation soil moisture content (i.e., porosity)	volumetric fraction
DKSAT	Saturated hydraulic conductivity	m/s
Runoff Parameters		
REFKDT	Surface runoff parameter	unitless
SLOPE	Linear scaling of "openness" of bottom drainage boundary	0-1
RETDEPRTFAC	Multiplier on retention depth limit	unit less
LKSATFAC	Multiplier on lateral hydraulic conductivity	unitless
Groundwater Parameters		
Zmax	Maximum groundwater bucket depth	mm
Expon	Exponent controlling rate of bucket drainage as a function of depth	dimensionless
Vegetation Parameters		
CWPVT	Canopy wind parameter for canopy wind profile formulation	1/m
VCMX25	Maximum carboxylation at 25C	umol/m ² /s
MP	Slope of Ball-Berry conductance relationship	unitless
Snow Parameters		
MFSNO	Melt factor for snow depletion curve	dimensionless
Channel Parameters		
ths	Saturated soil water content	volumetric fraction
thin	Initial soil water content	volumetric fraction
al	Pore size distribution index	unitless
g	Mean capillary drive	m

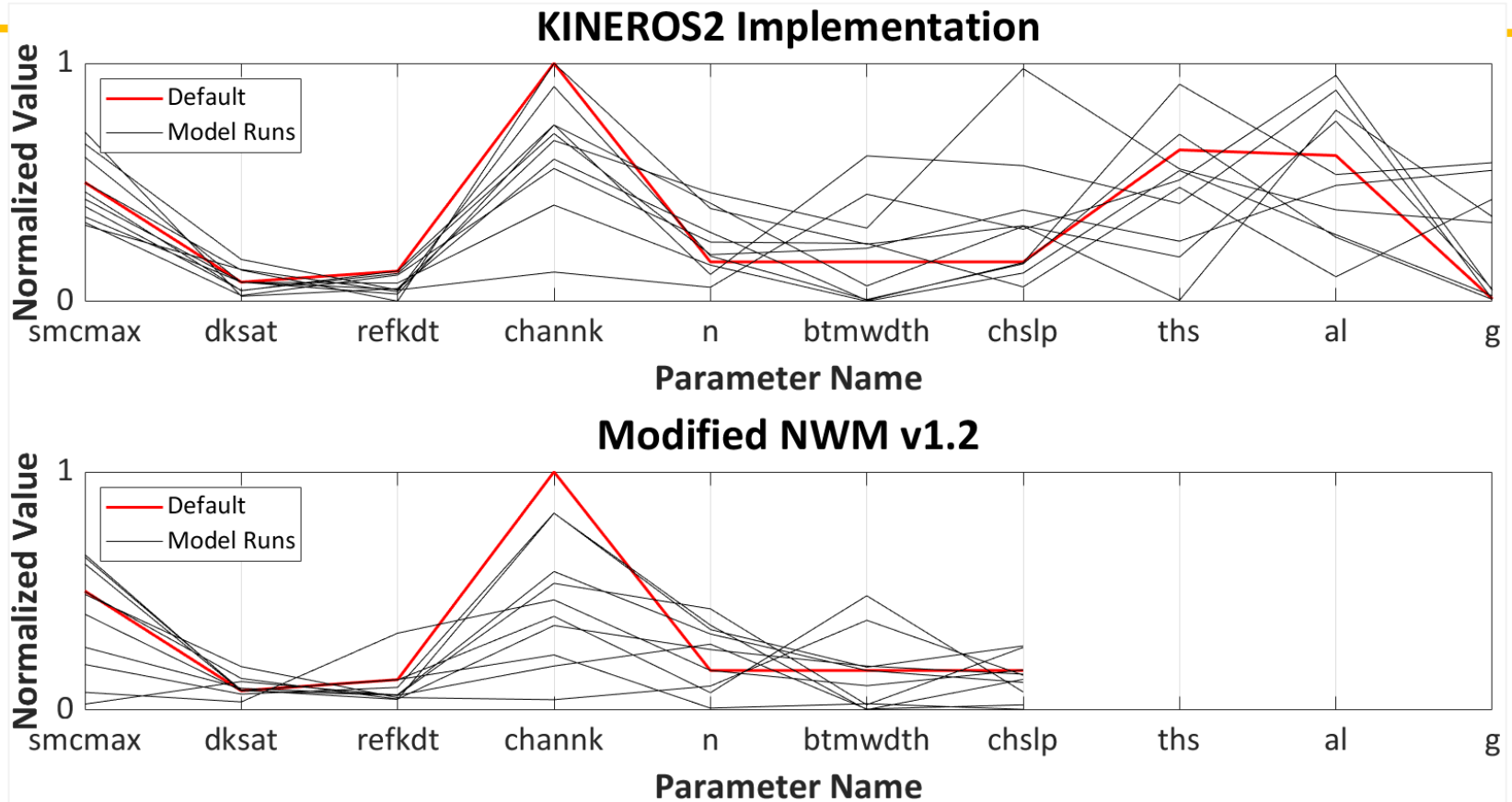
Selected Parameters (10 PAR)

Name	Description	Units
Soil Parameters		
SMCMAX	Saturated soil moisture content (i.e., porosity)	volumetric fraction
DKSAT	Saturated hydraulic conductivity	m/s
Runoff Parameters		
REFKDT	Surface runoff parameter (partitioning of total runoff into surface and subsurface runoff)	Unitless
Channel Parameters		
ChannK	Channel bed conductivity (for channel infiltration function)	m/s
btmwidth	Bottom width of Channel	m
ChSlp	Channel side slope	Unitless
n	Manning's N	s/m ^{1/3}
ths	Saturated soil water content	volumetric fraction
al	Pore size distribution index	unitless
g	Mean capillary drive	m

Calibration on the Real Data



Uncertainty in Best Parameter



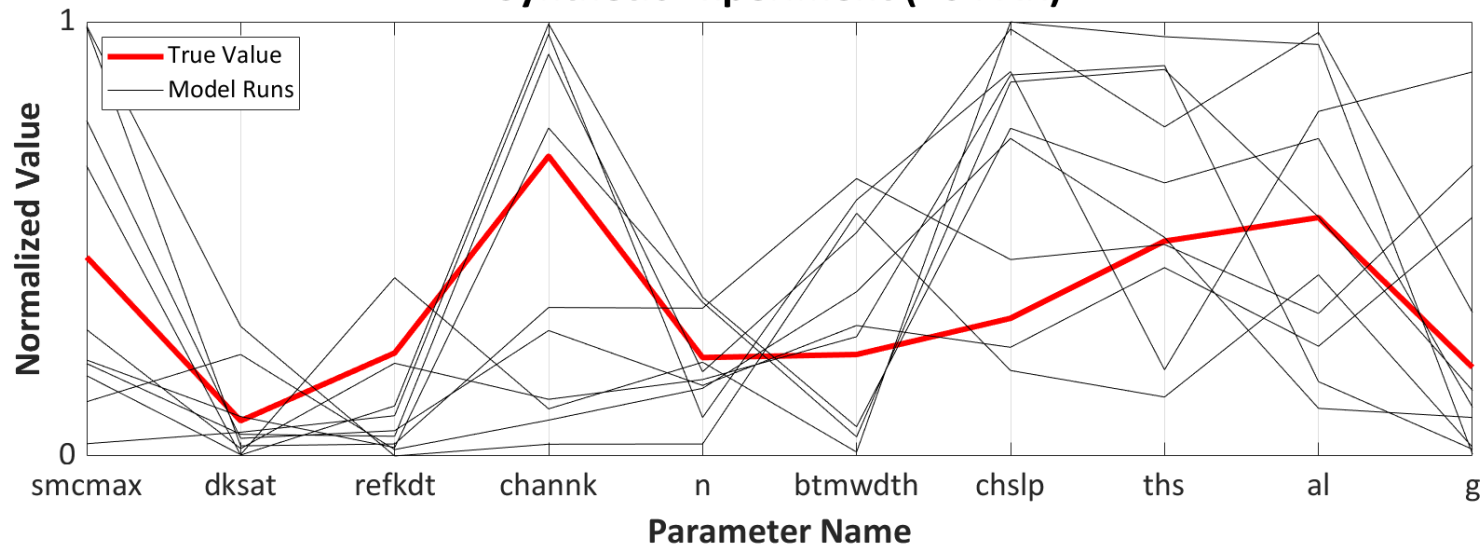
- ✓ Both NWM versions suggest that only two LSM parameters “*dksat*” and “*refkdt*” are sensitive.
- ✓ Capillary Drive “*g*” seems to be the most sensitive parameter among other three new added channel parameters

Synthetic Experiment (SE)

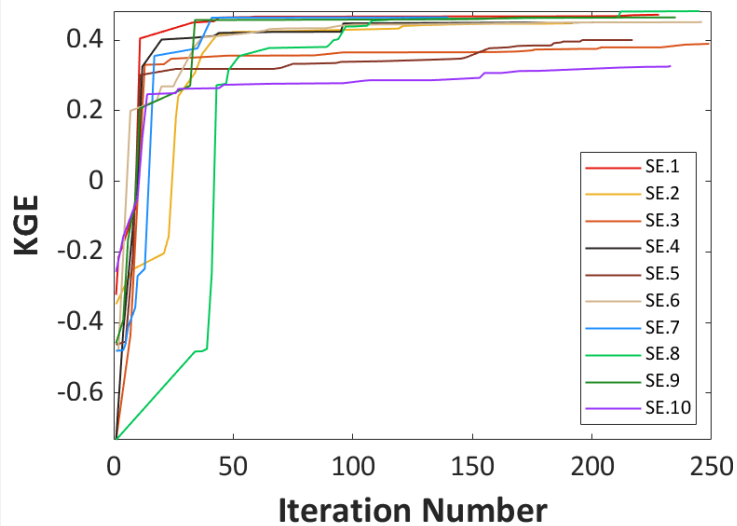
- Remove the model/data error
 - Use the “*median*” of 10 best parameter value as “*true value*”
- Simulation:
 - Fix nine parameters at their “*true value*” and perturbed one parameter at a time
 - Examine the effects that each parameter plays on the hydrograph
- Calibration:
 - Use the same “*first searching direction*” of previous 10 DDS runs
 - Calibrate 10 parameters (10 runs) using 250 DDS iterations
 - Calibrate 9 parameters (10 runs) using 250 DDS iterations (Remove “*Channk*”)
 - Calibrate 6 parameters (10 runs) using 250 DDS iterations (Remove “*Channk*” and three parameters in Noah-MP LSM)

SE (10 PAR)

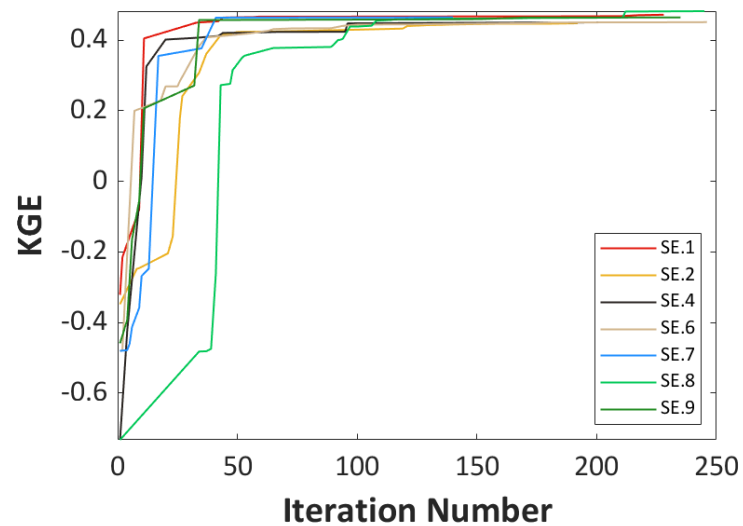
Synthetic Experiment (10 PAR)



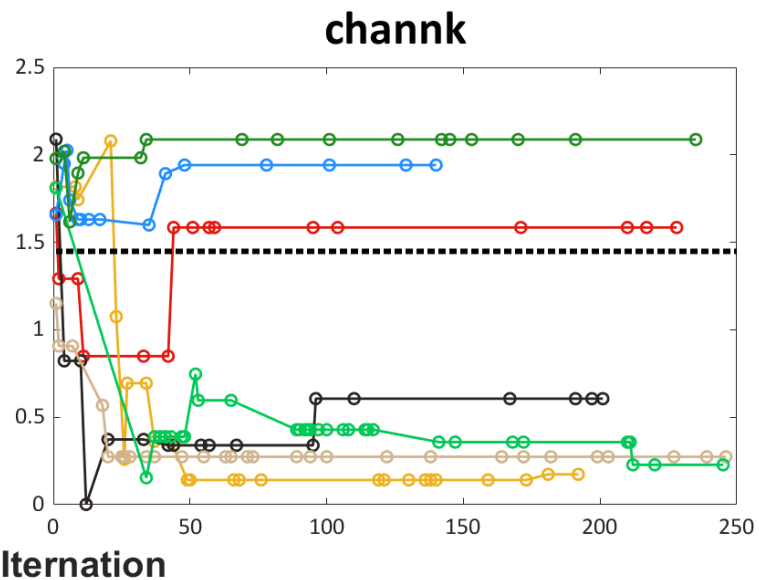
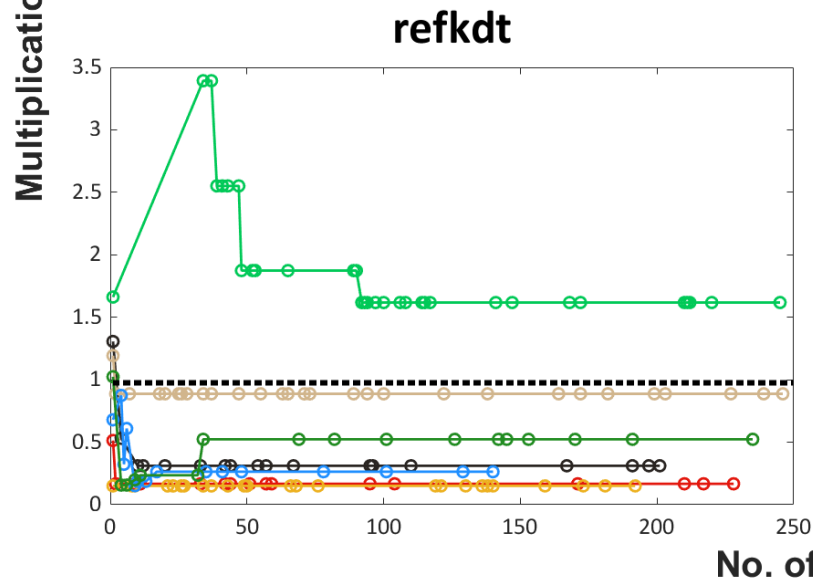
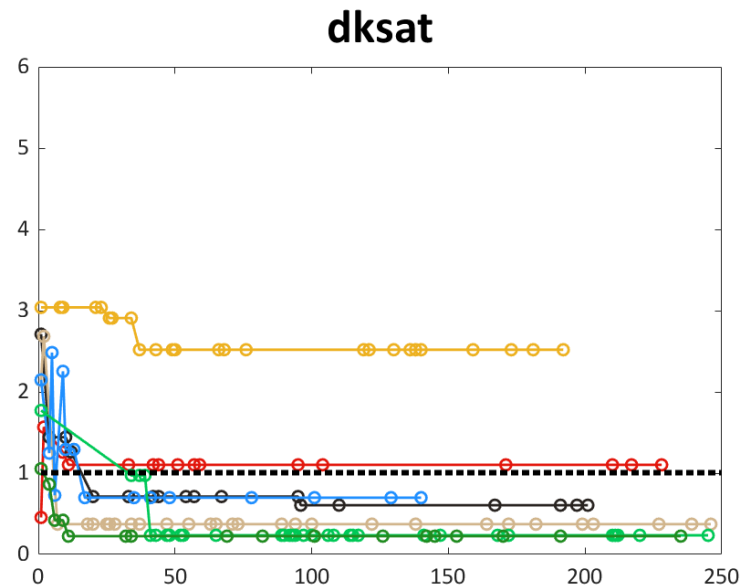
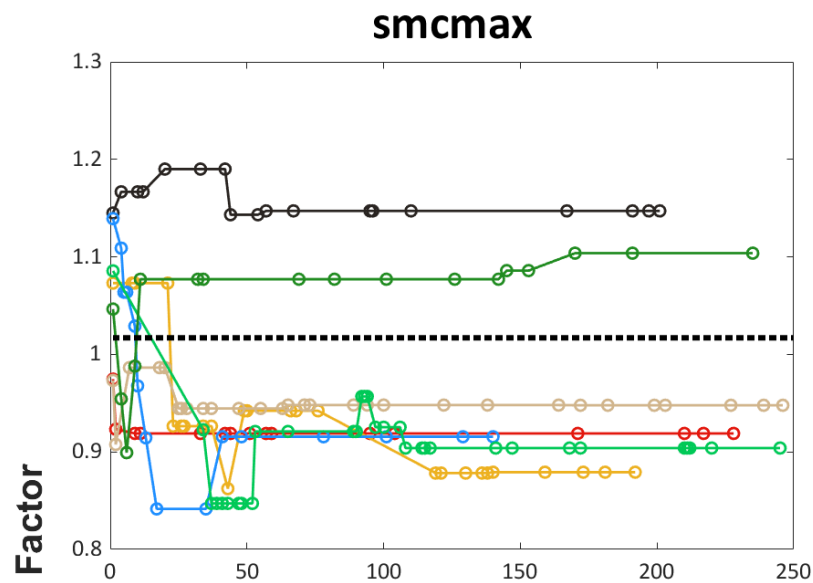
Objective Function



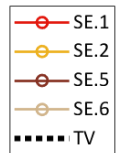
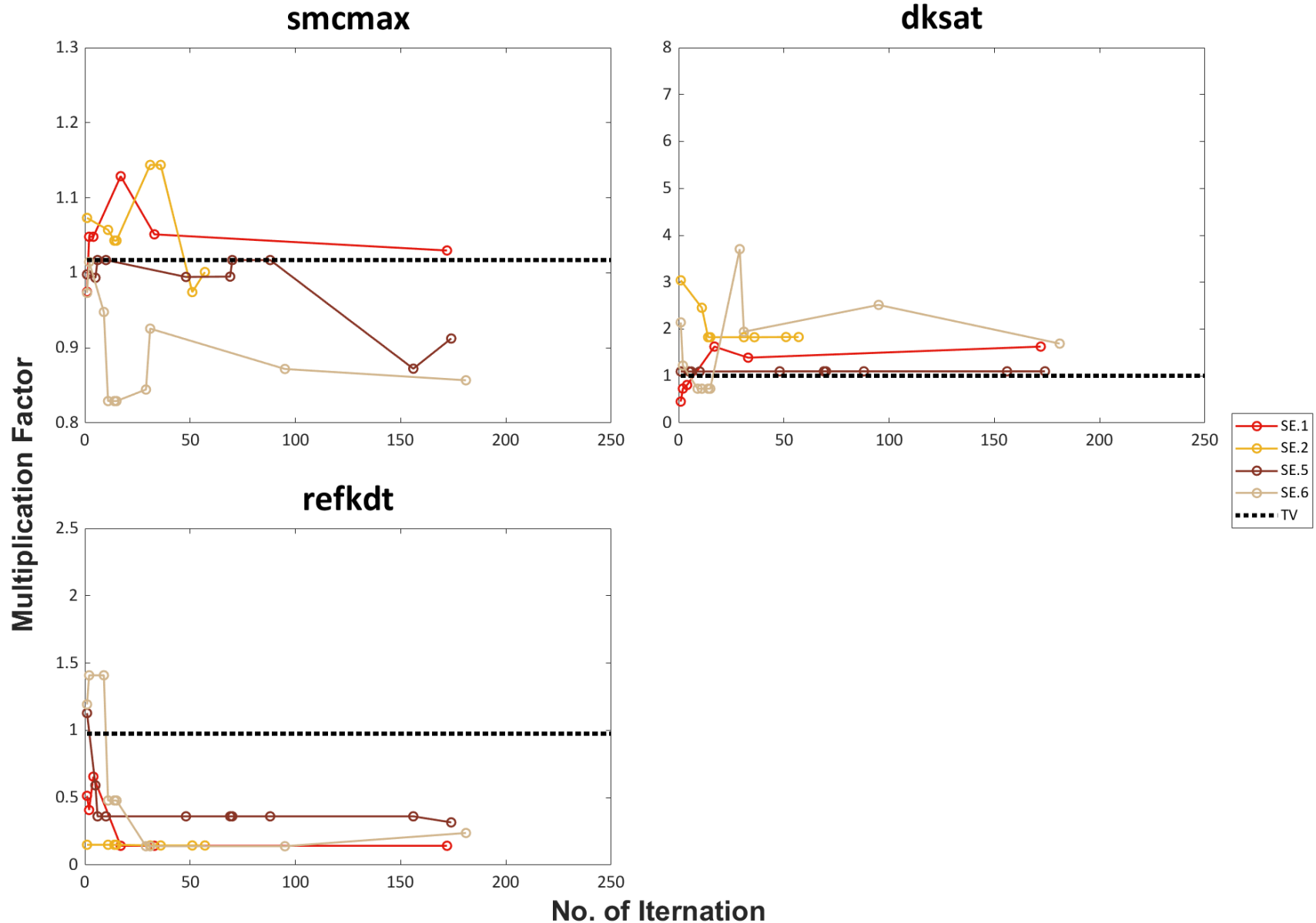
Objective Function



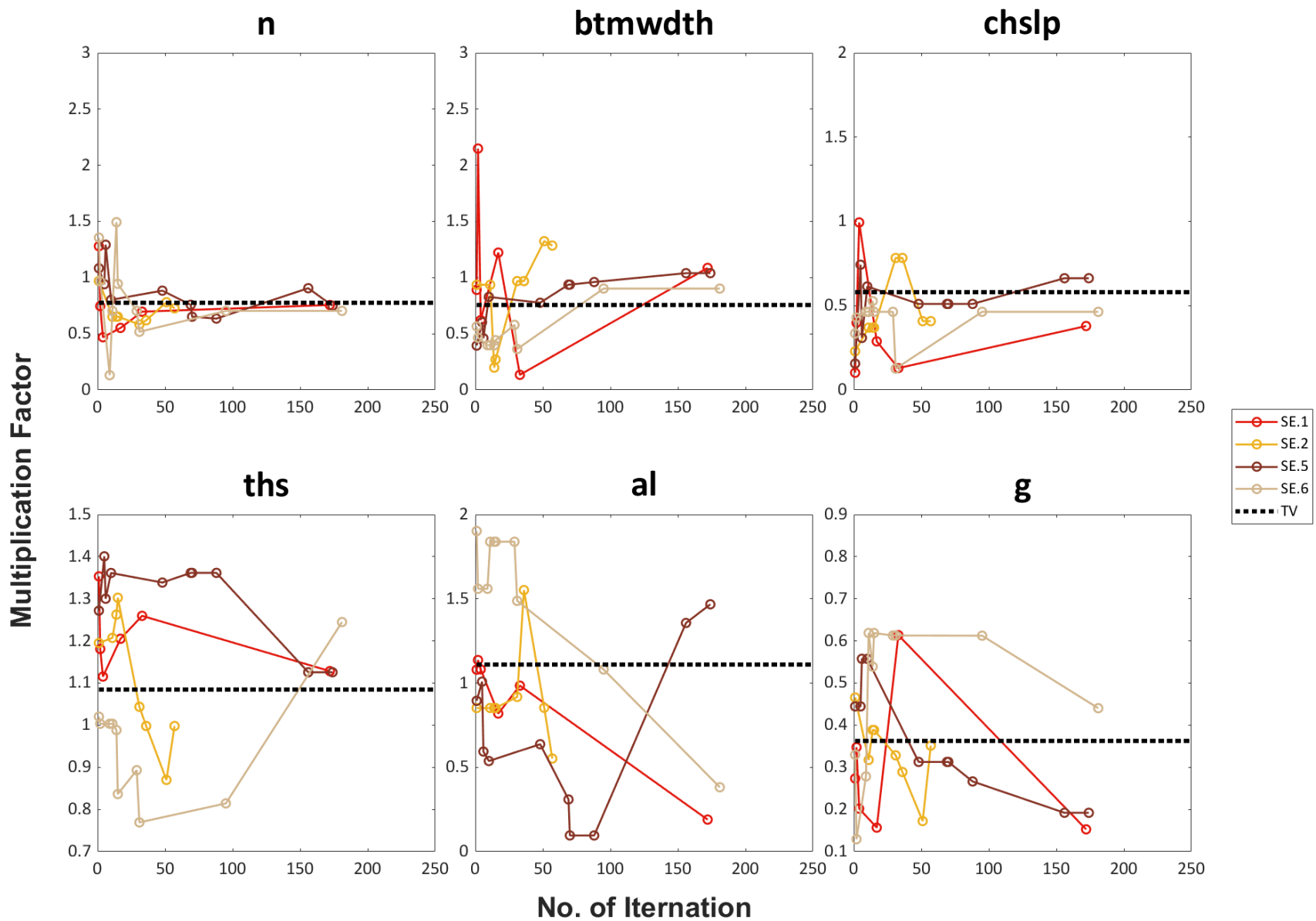
SE (10 PAR)



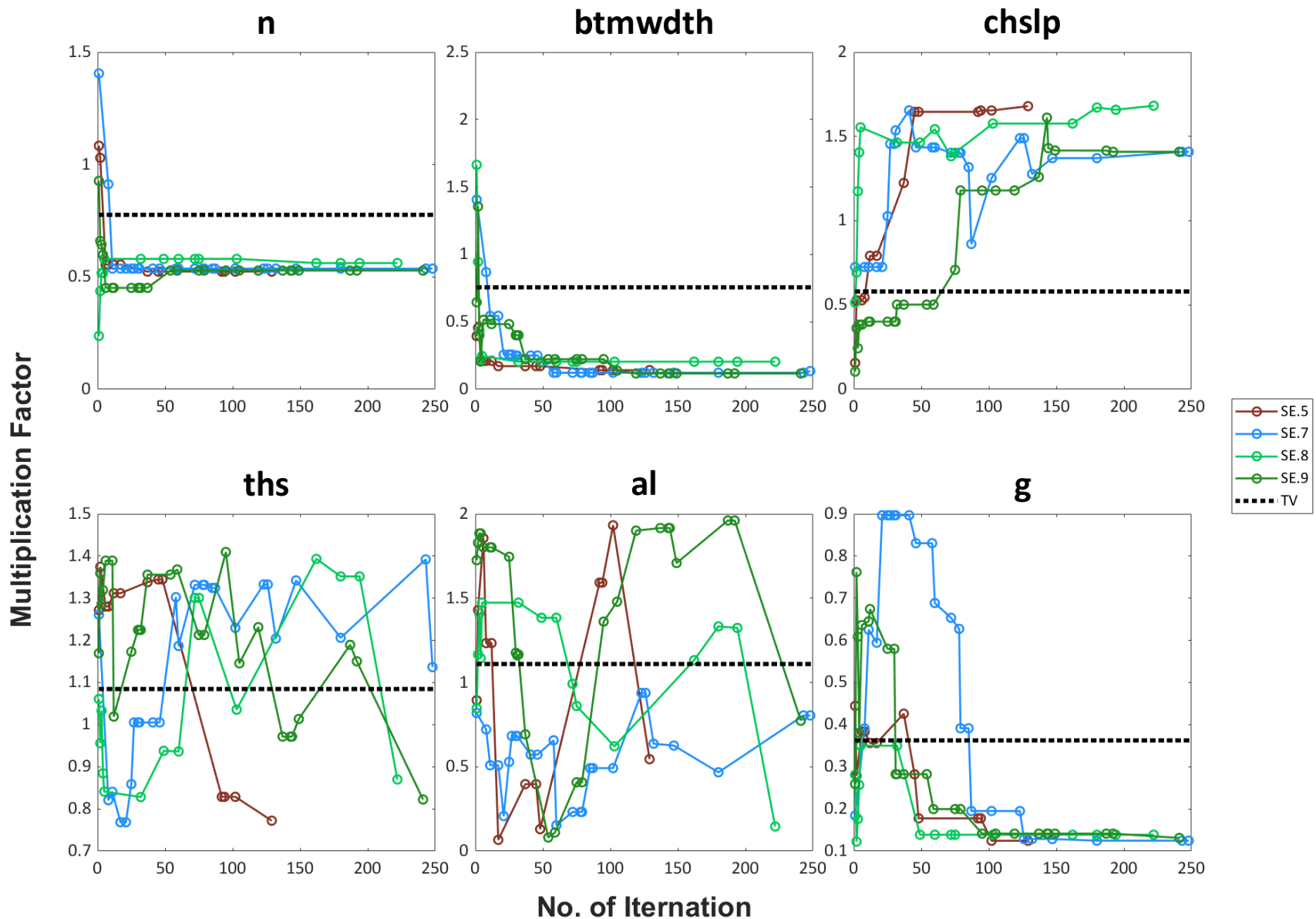
SE (9 PAR)-Fixed ChannK



SE (9 PAR)-Fixed ChannK



SE (6 PAR)-Fixed ChannK & LSM PAR



Conclusions & Future Research

- Our implementation of the updated infiltration scheme works for semi-arid region
- It is not ideal to calibrate all 10 parameter at one time
- In the synthetic experiment the calibrated parameters did not converge to the “true value” for any demonstrated cases
- The reason may be:
 - The data contains insufficient information
 - The interdependence between different parameters leads to compensation while searching for the optimum
 - The selected objective function (KGE) is *not sensitive* to the channel “infiltrability” at the beginning of the flow event

An aerial photograph of a university campus during the golden hour. The foreground and middle ground are filled with large, multi-story buildings featuring prominent red-tiled roofs and light-colored walls. Some buildings have multiple stories with many windows. The campus is interspersed with green trees, including palm trees. In the background, a range of rugged, brown mountains stretches across the horizon under a clear blue sky with a few wispy clouds. A single white contrail from an aircraft is visible in the upper right portion of the sky.

Thank You
(Question?)